

First Generalized Embodiment

FIG. 1A

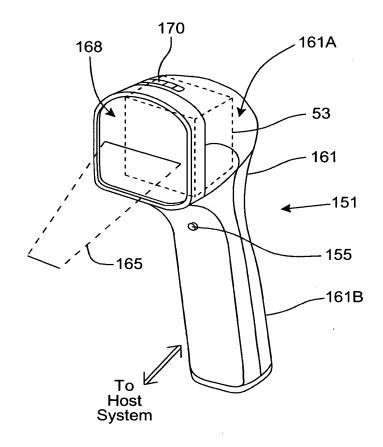


FIG. 1B

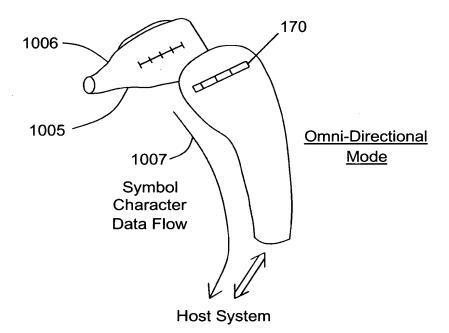


FIG. 2A

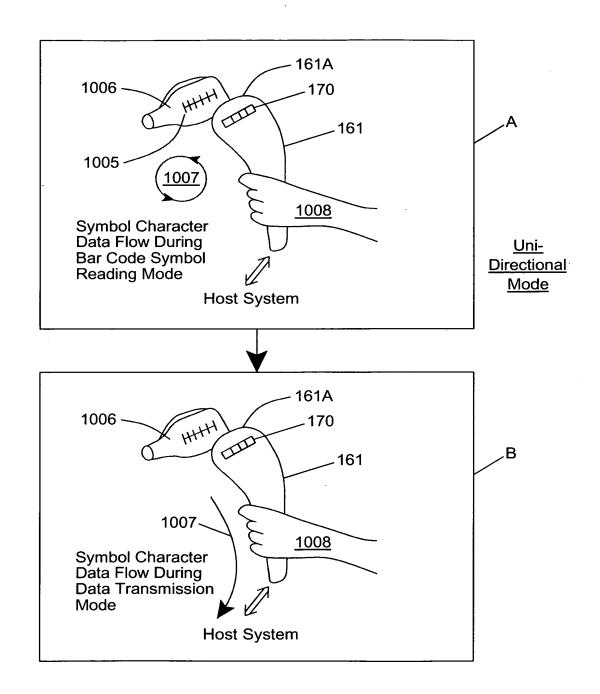
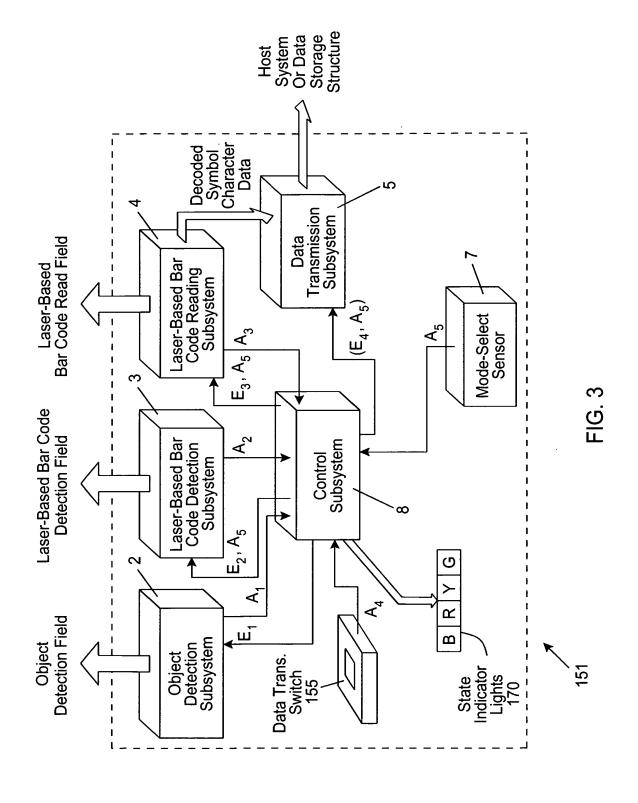
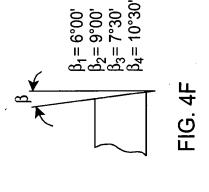


FIG. 2B





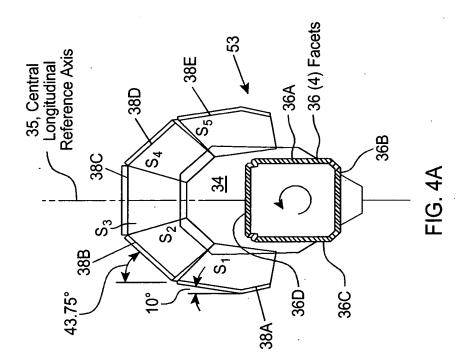


FIG. 4E

Bend 0

Twist α 46.0°

10°

S₁₋₅

42.5°

S₂₋₄

40.5°

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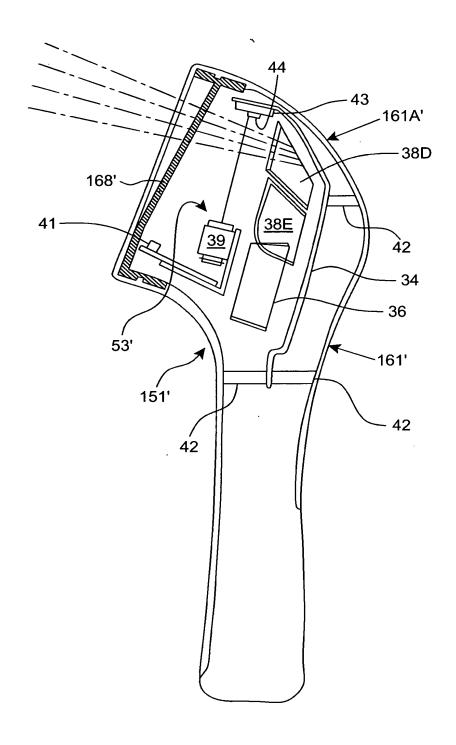


FIG. 4B

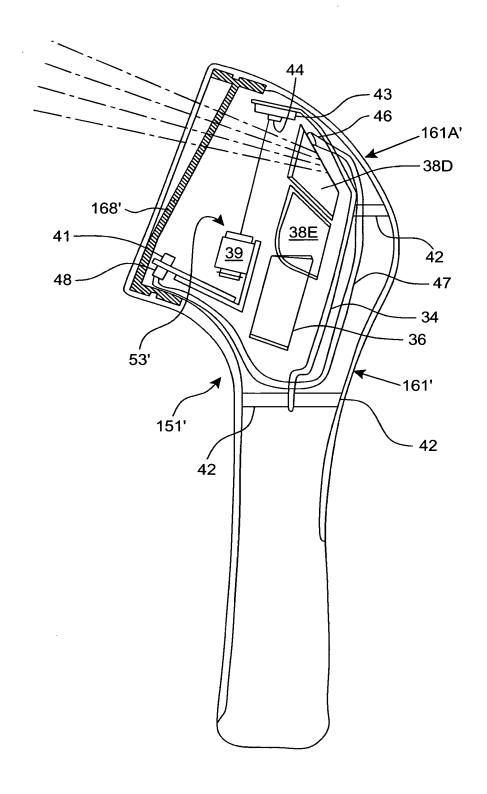


FIG. 4C

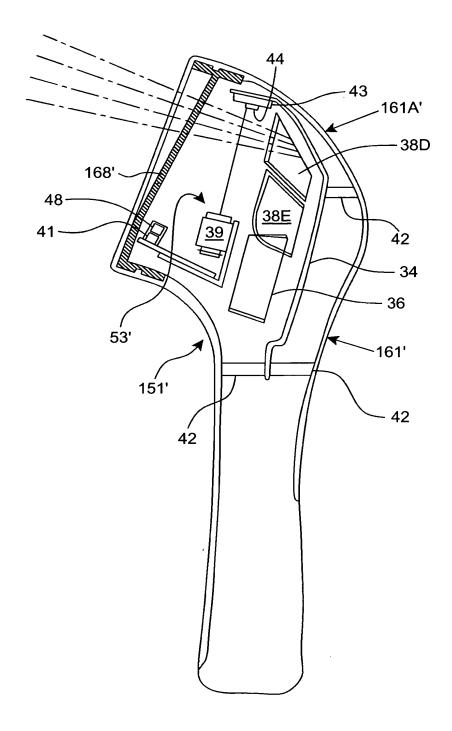


FIG. 4D1

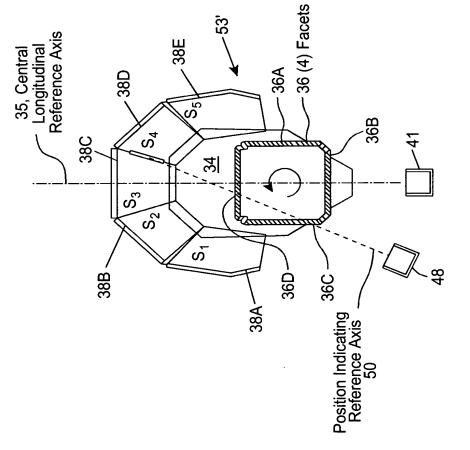


FIG. 4D2

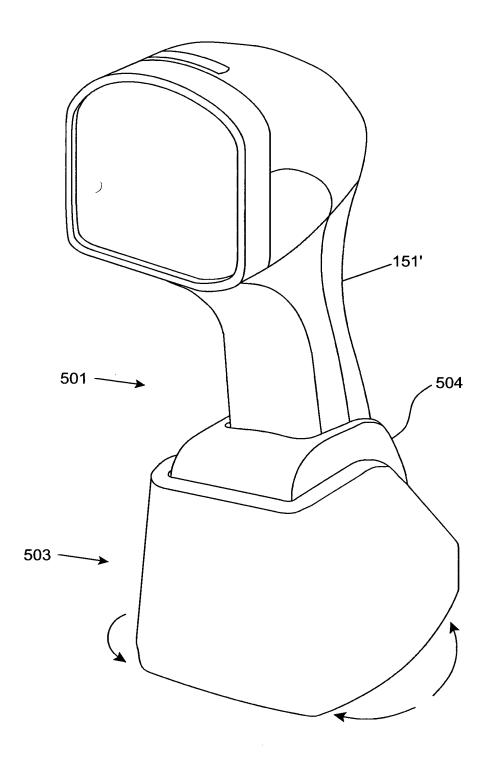


FIG. 5A

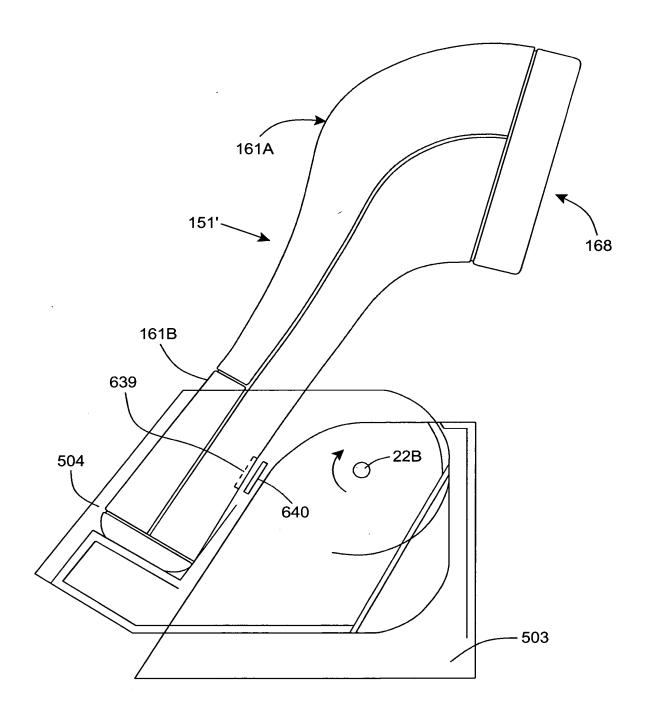
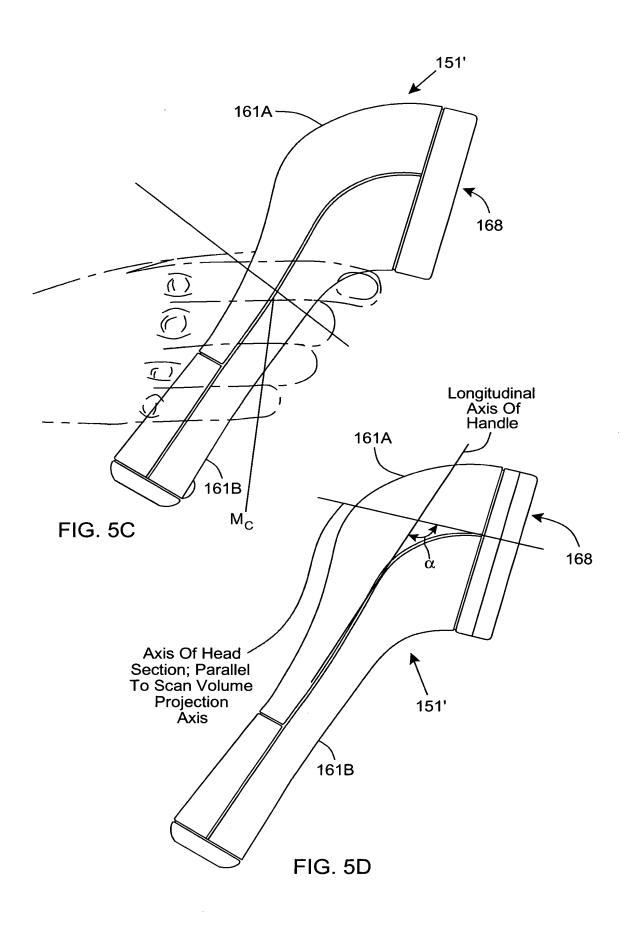


FIG. 5B



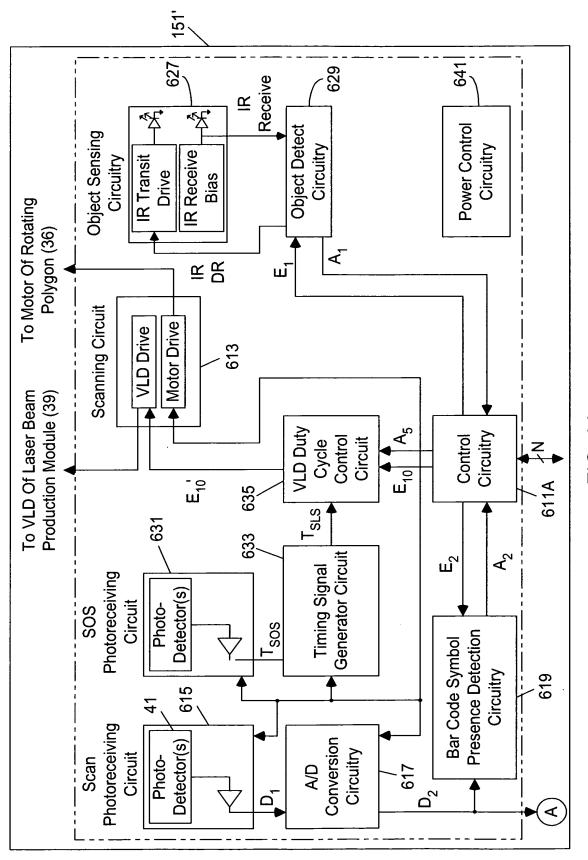
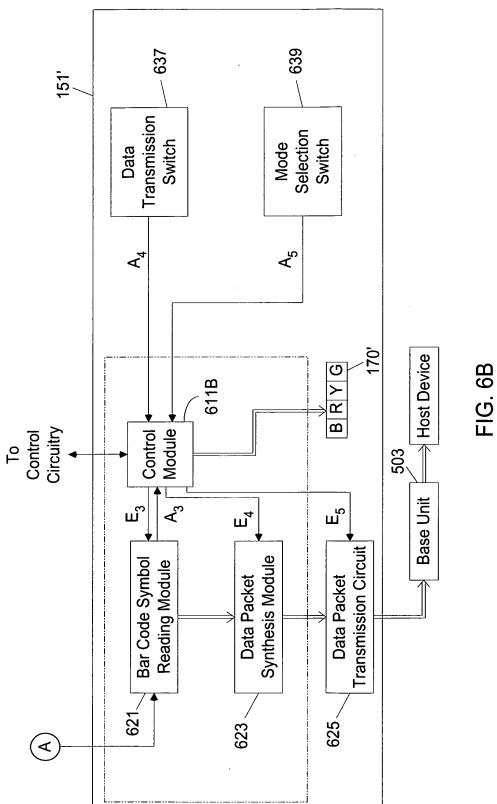


FIG. 6A



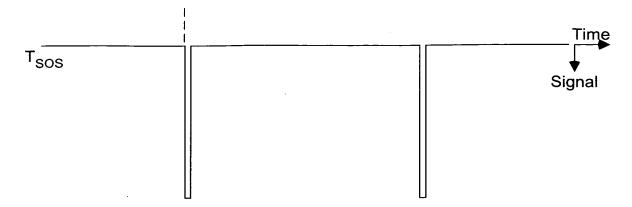


FIG. 7A

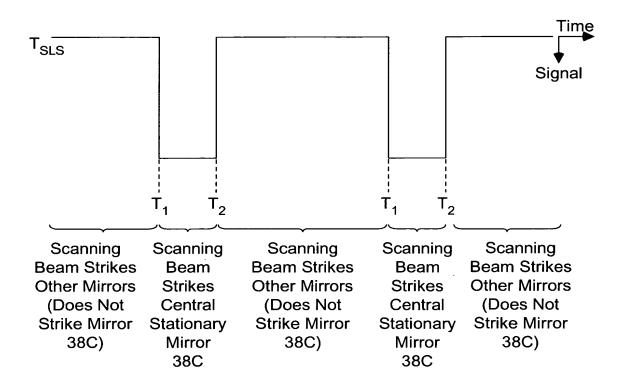


FIG. 7B

$$E_{10}' = (\overline{T_{SLS}} \times E_{10} \times A_5) + (E_{10} \times \overline{A_5})$$
FIG. 7C

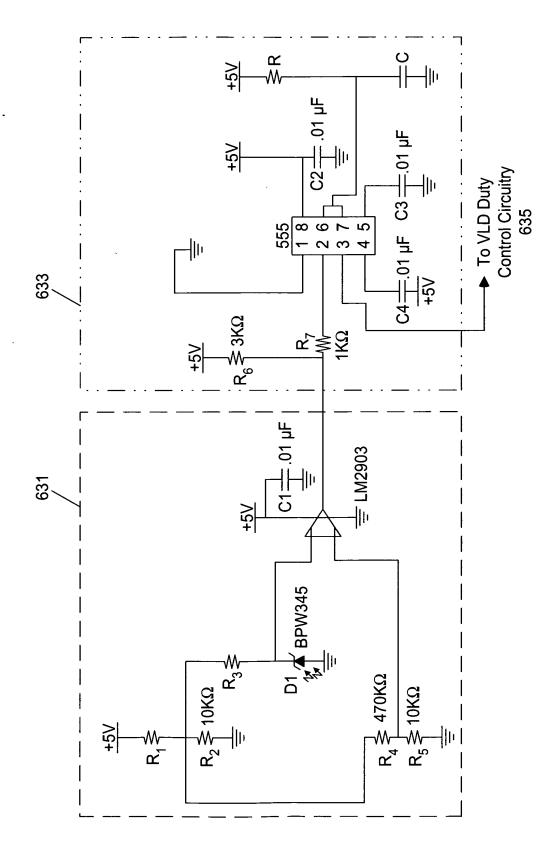


FIG. 7D

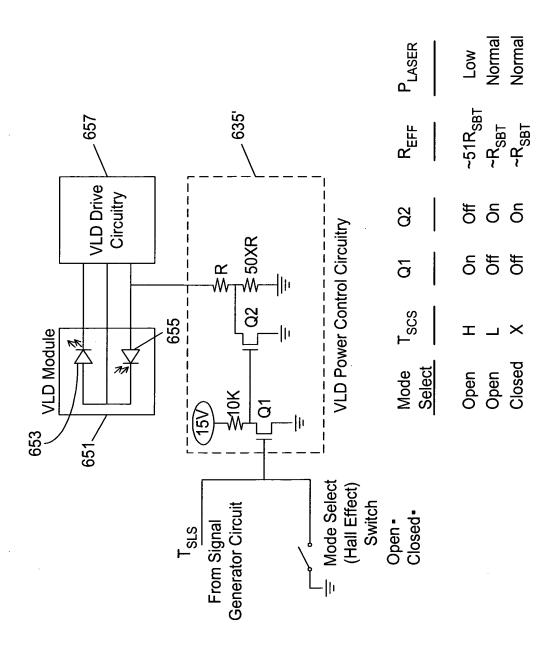


FIG. 7E

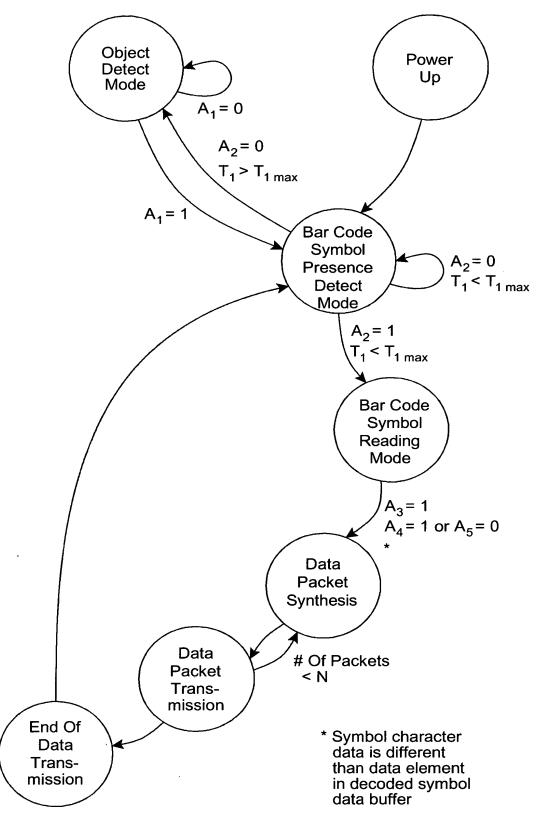
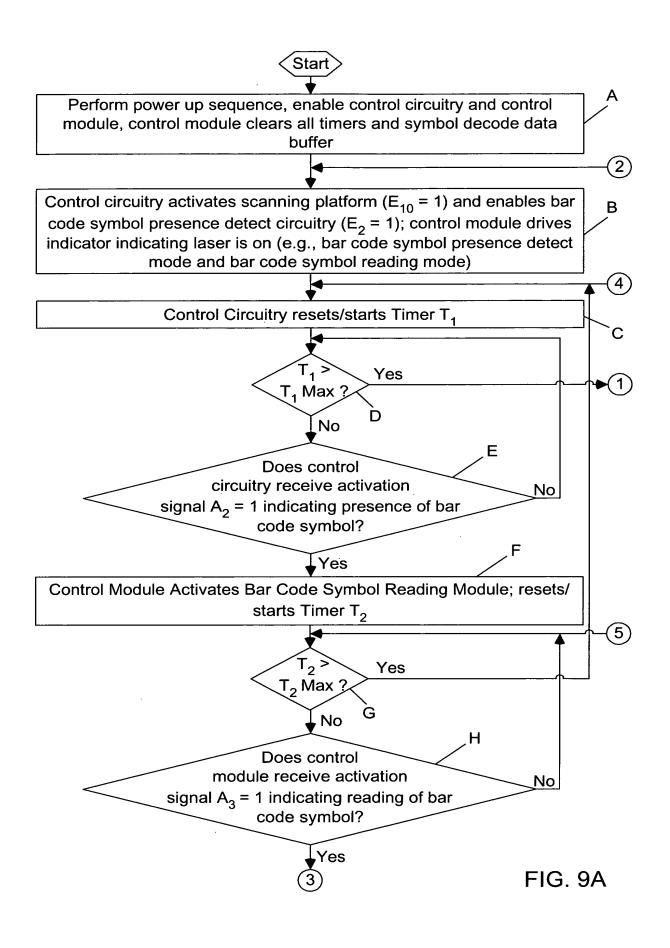
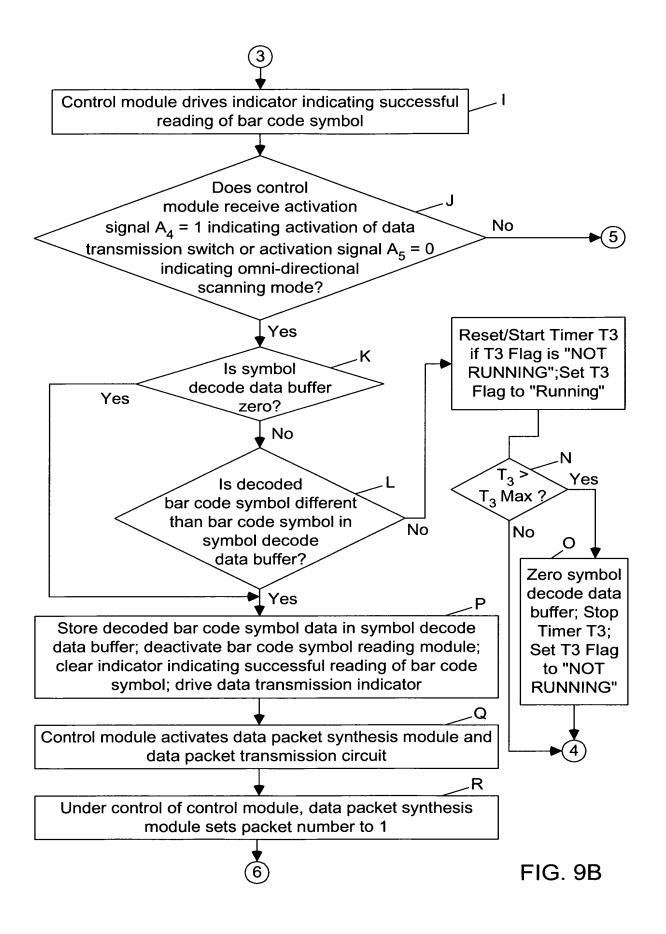


FIG. 8





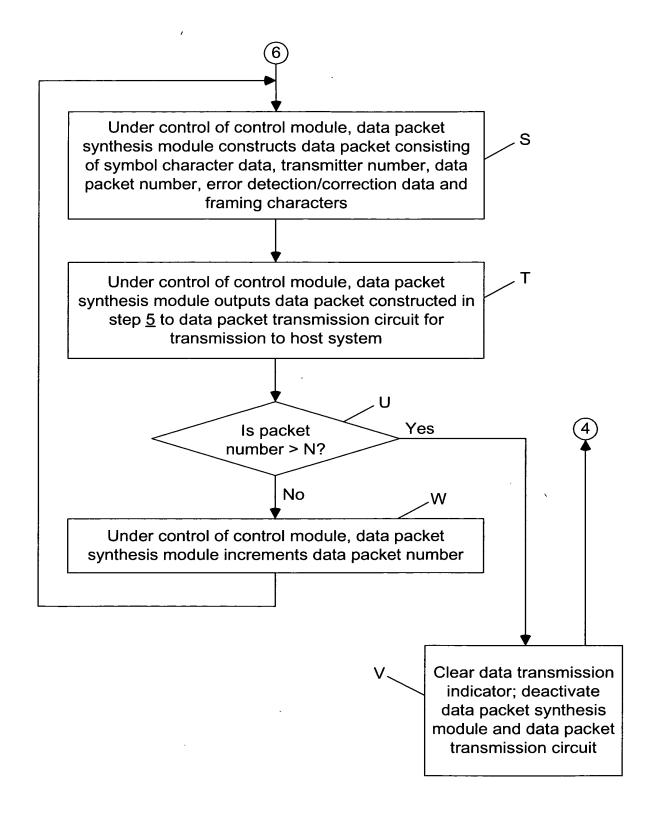


FIG. 9C

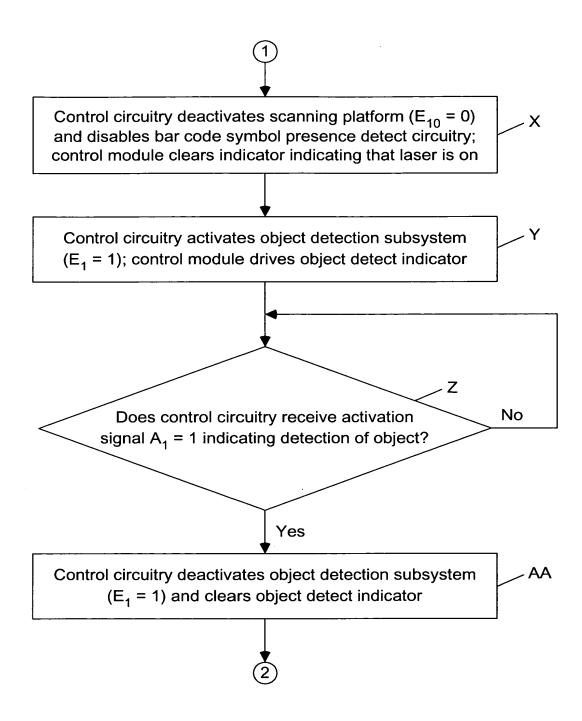
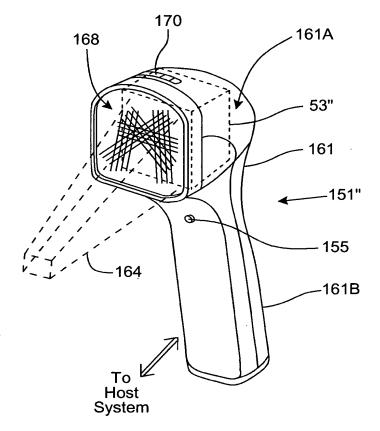


FIG. 9D



Second Generalized Embodiment

FIG. 10A

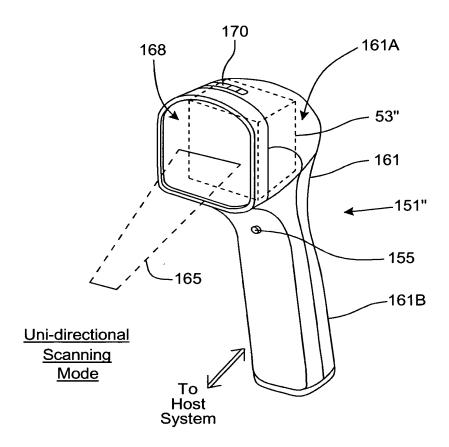


FIG. 10B

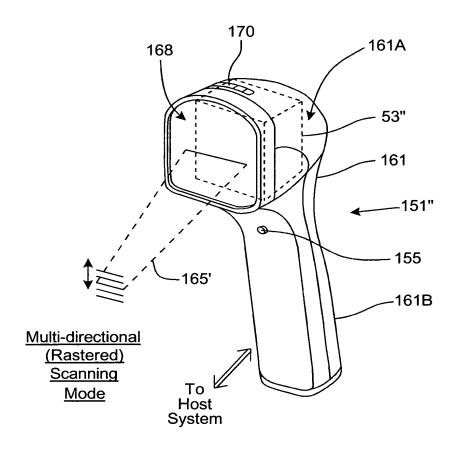


FIG. 10C

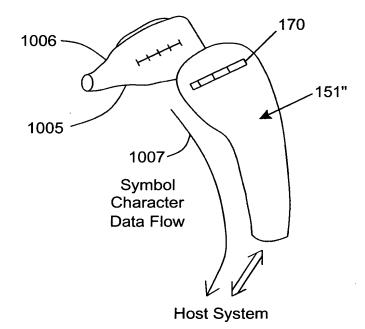


FIG. 11A

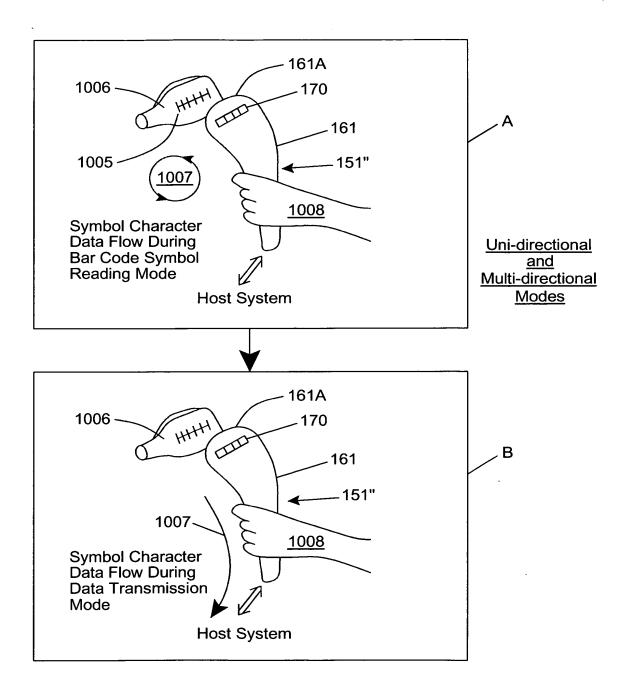
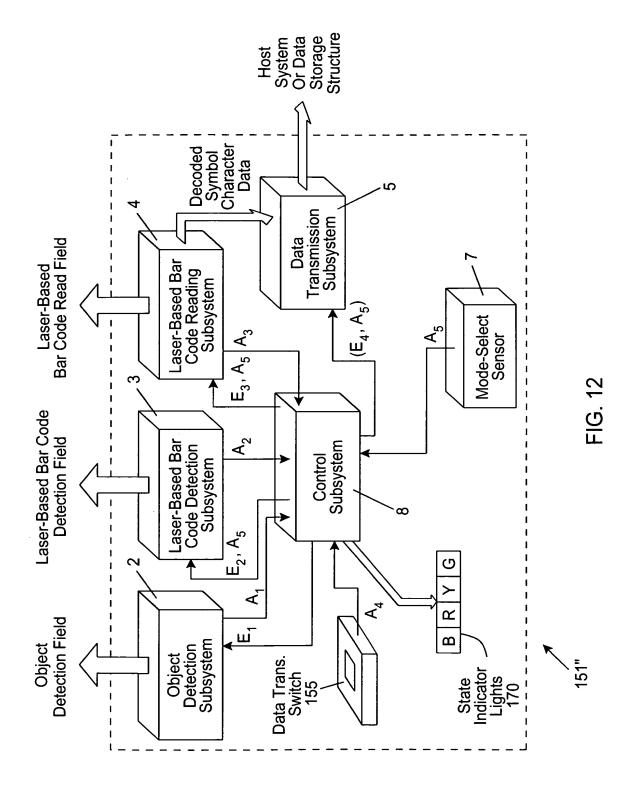


FIG. 11B



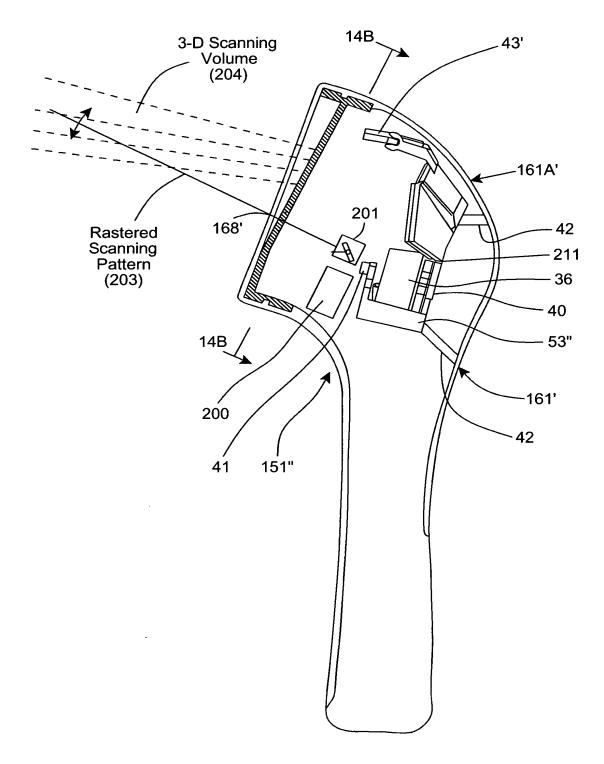


FIG. 13

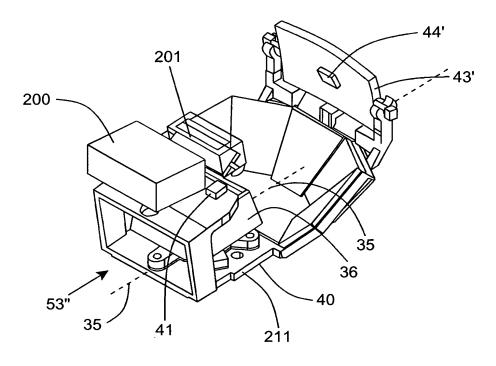


FIG. 14A

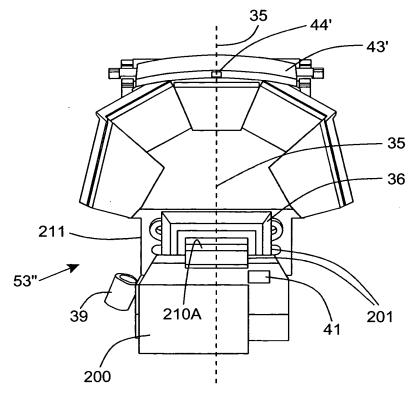


FIG. 14B

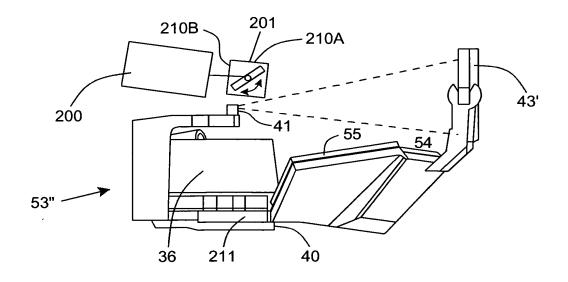


FIG. 14C

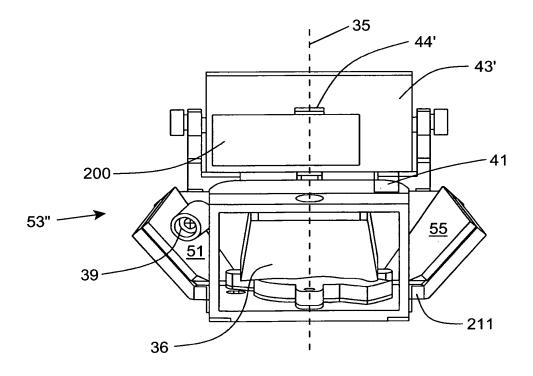


FIG. 14D

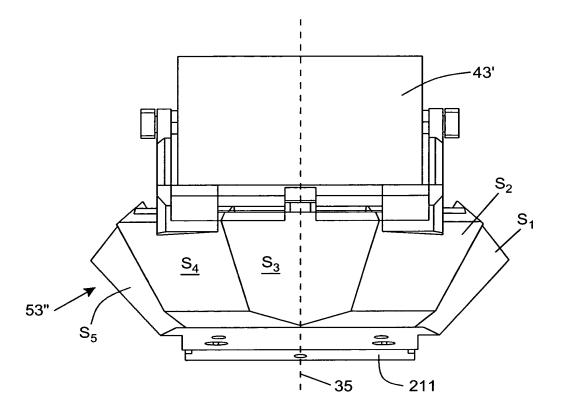


FIG. 14E

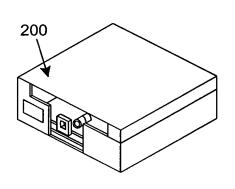


FIG. 14F

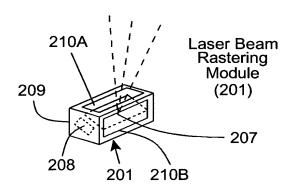


FIG. 14G

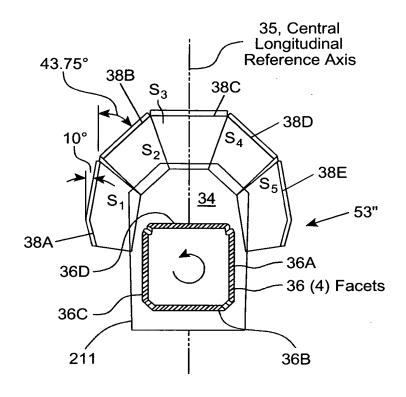


FIG. 15A

Optics Bench Array Mirror Specifications

Mirror	Relief Angle	Twist Angle
	Degrees	
1	45.91	69.32
2	47.85	34.15
3	48.4	0
4	47.85	34.15
5	45.91	69.32

Mirror	Length	Width
	Millimeters	
1 2 3 4	19.872 16.341 16.67 16.341	17.303 13.746 15.788 13.746
5	19.872	17.303

FIG. 15B

Angles Specification:

Definitions:

Relief Angle- The angle between the plane including all the bottom front edges of the array mirrors and the front surface of the mirror being measured.

Twist Angle- The angle of rotation about the z-axis with 0 degrees twist being defined as perpendicular to the incident beam (field 3).

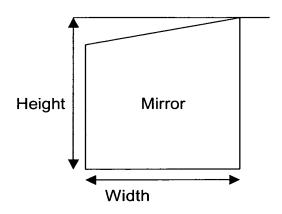


FIG. 15C

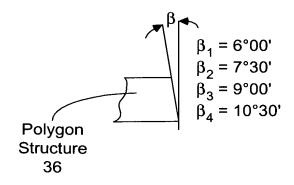


FIG. 15D

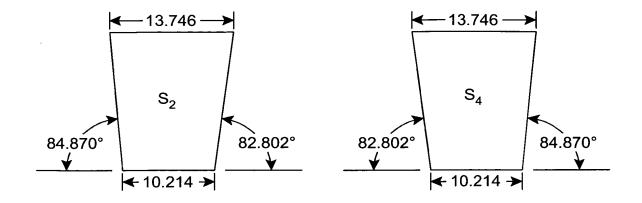
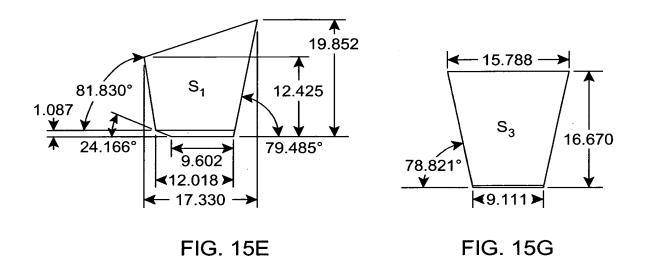


FIG. 15F

FIG. 15H



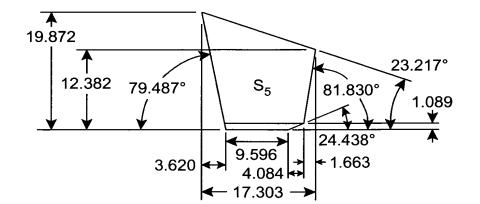


FIG. 151

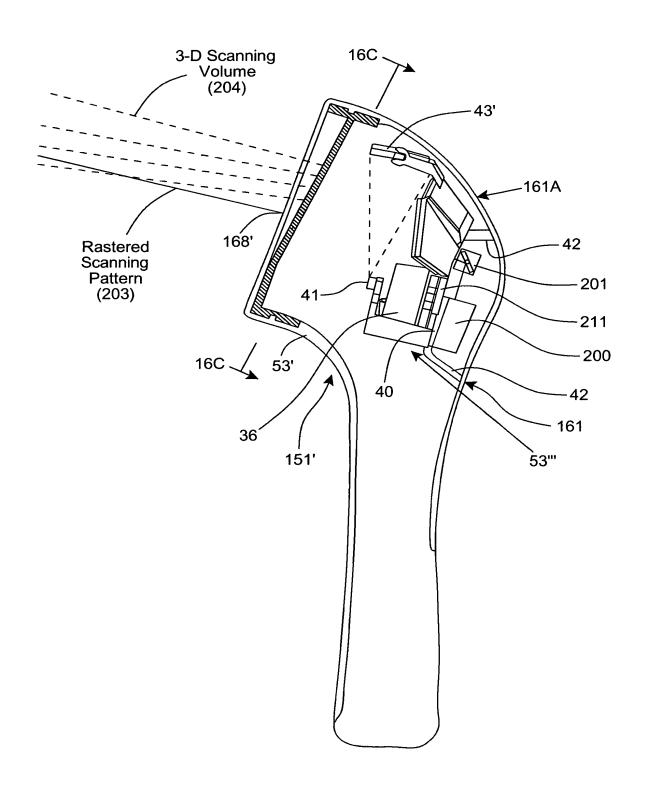


FIG. 16A

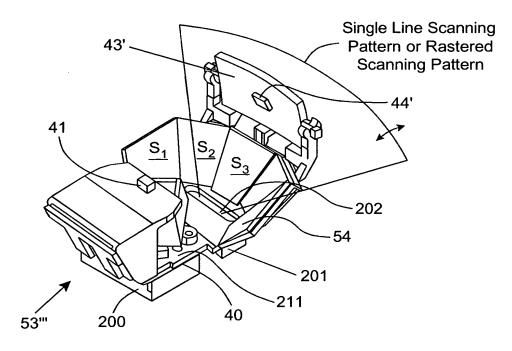


FIG. 16B

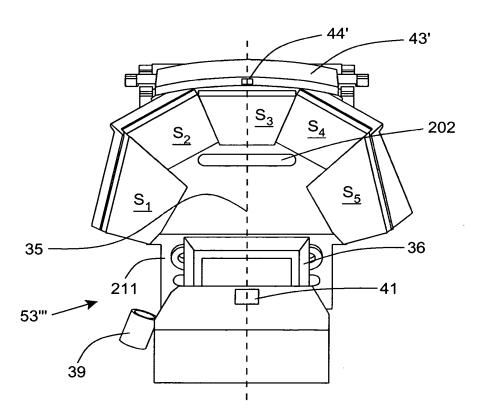


FIG. 16C

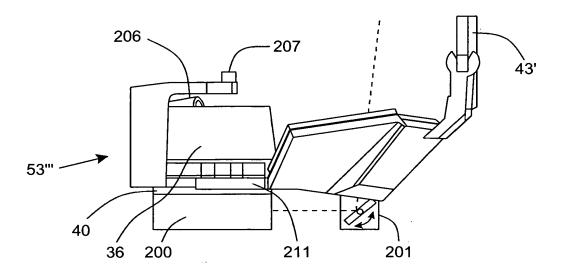


FIG. 16D

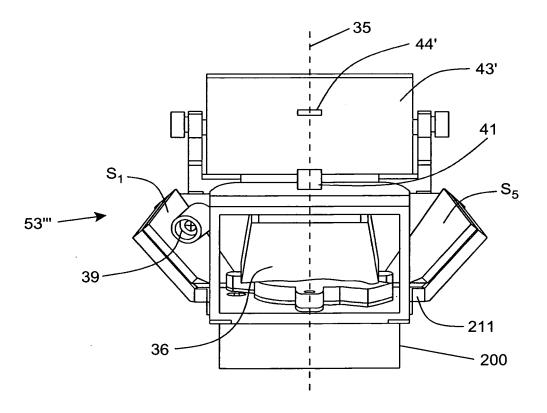


FIG. 16E

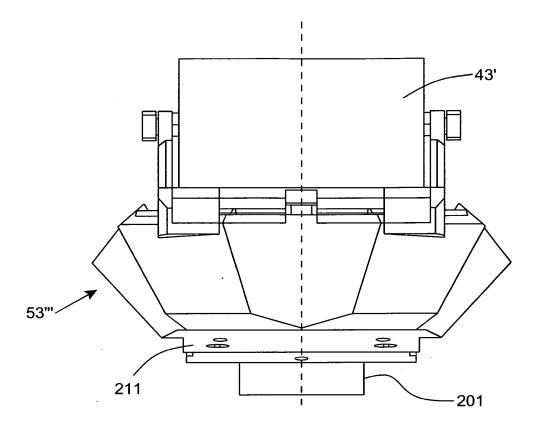


FIG. 16F

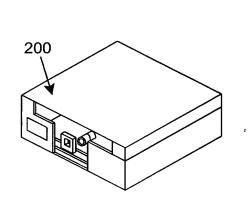


FIG. 16G

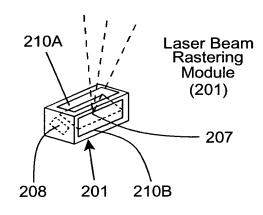


FIG. 16H

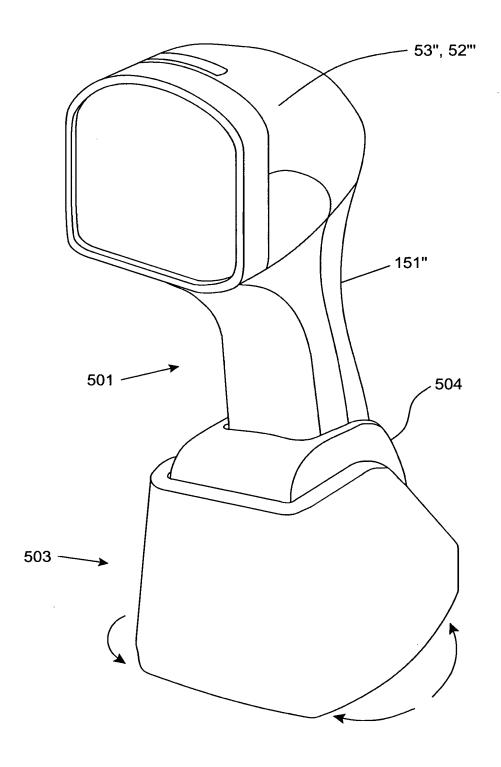
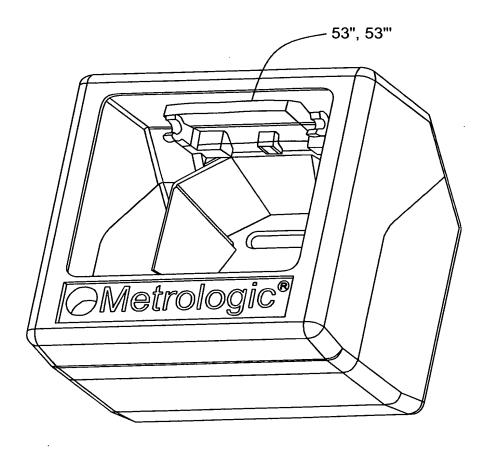


FIG. 17



Device Has Omni-directional, Multi-directional, and Uni-directional Scanning Modes of Operation

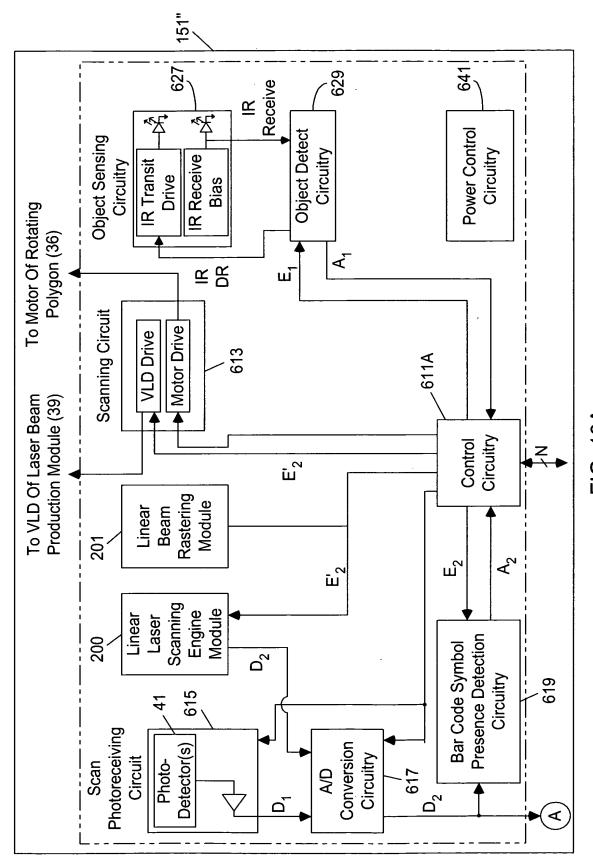


FIG. 19A

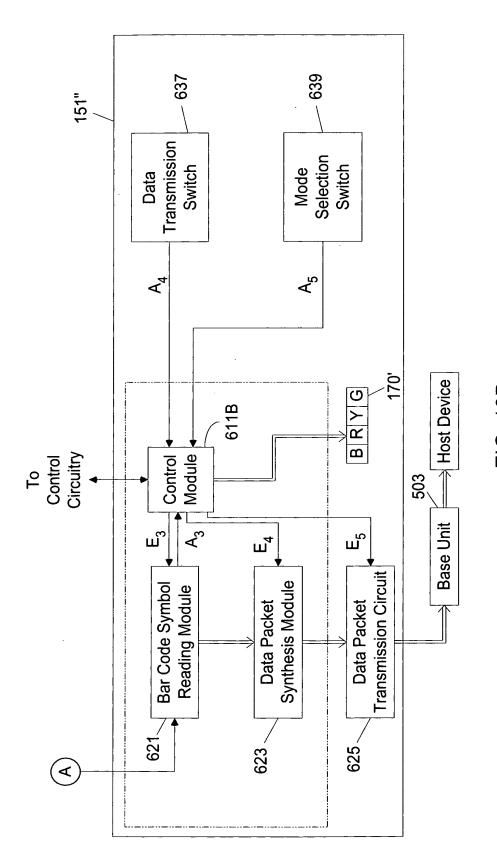


FIG. 19B

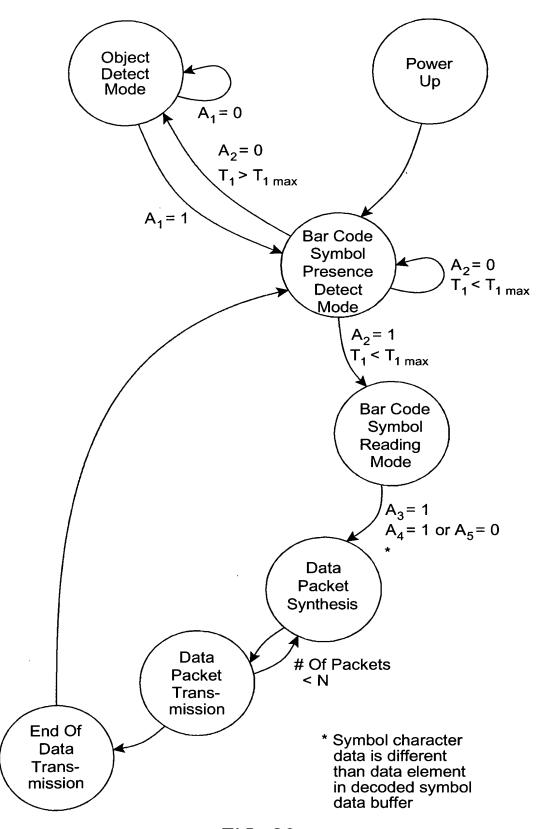
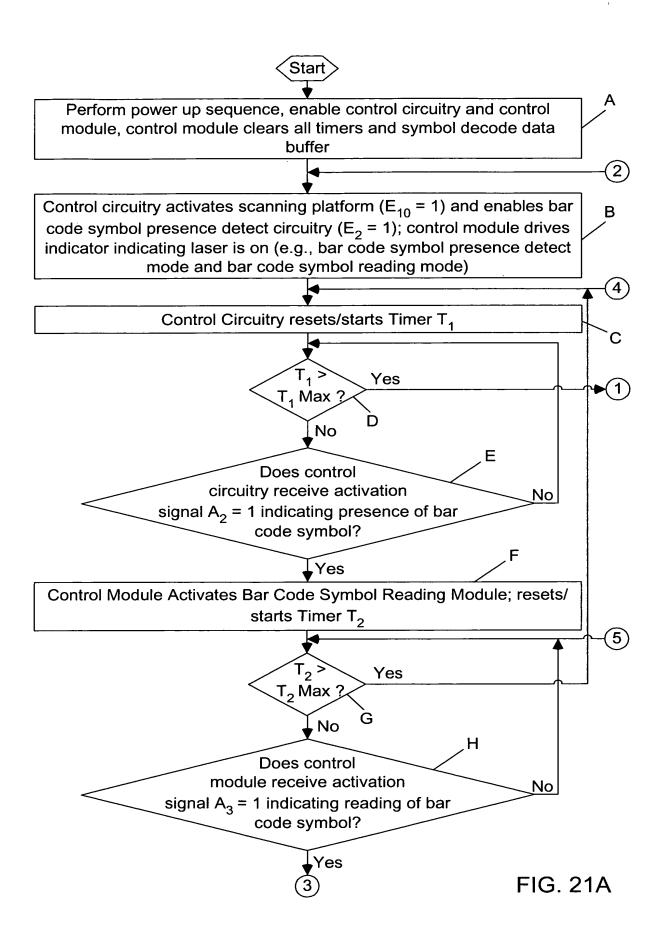
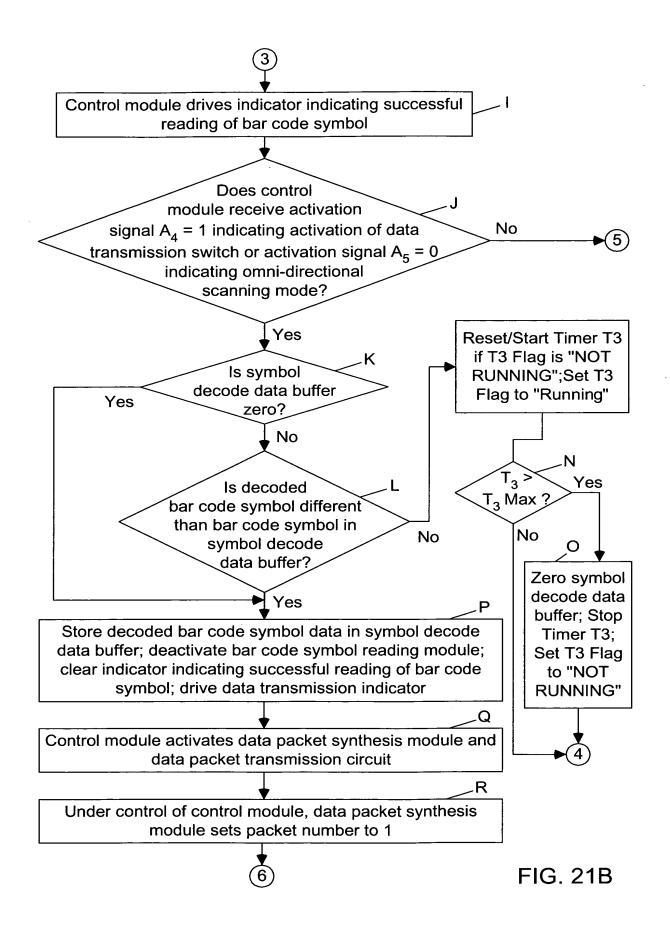


FIG. 20





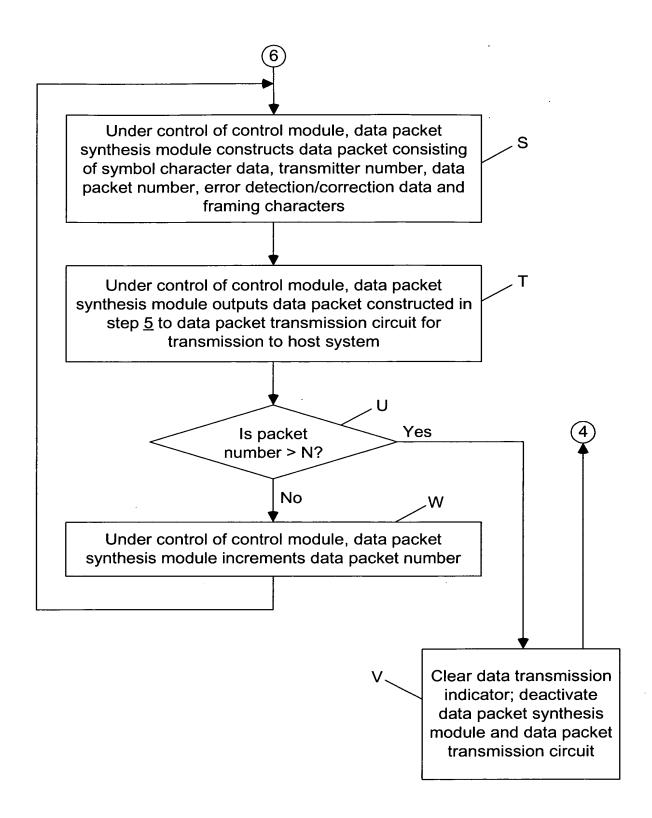


FIG. 21C

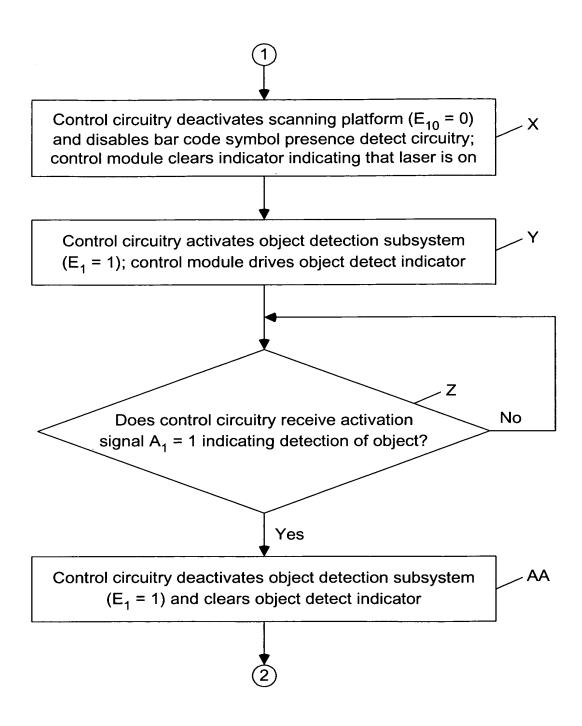


FIG. 21D